(iii) Relations between the basis vectors $\mathbf{a}^{\prime}, \mathbf{b}^{\prime}$ of the plane group and the basis vectors $\mathbf{a}, \mathbf{b}, \mathbf{c}$ of the space group. Each set of basis vectors refers to the conventional coordinate system of the plane group or space group, as employed in Parts 6 and 7. The basis vectors of the two-dimensional cell are always called $\mathbf{a}^{\prime}$ and $\mathbf{b}^{\prime}$ irrespective of which two of the basis vectors $\mathbf{a}, \mathbf{b}, \mathbf{c}$ of the threedimensional cell are projected to form the plane cell. All relations between the basis vectors of the two cells are expressed as vector equations, i.e. $\mathbf{a}^{\prime}$ and $\mathbf{b}^{\prime}$ are given as linear combinations of $\mathbf{a}, \mathbf{b}$ and c. For the triclinic or monoclinic space groups, basis vectors $\mathbf{a}, \mathbf{b}$ or $\mathbf{c}$ inclined to the plane of projection are replaced by the projected vectors $\mathbf{a}_{p}, \mathbf{b}_{p}, \mathbf{c}_{p}$.

For primitive three-dimensional cells, the metrical relations between the lattice parameters of the space group and the plane group are collected in Table 2.2.14.1. The additional relations for centred cells can be derived easily from the table.
(iv) Location of the origin of the plane group with respect to the unit cell of the space group. The same description is used as for the location of symmetry elements ( $c f$. Section 2.2.9).

## Example

'Origin at $x, 0,0$ ' or 'Origin at $\frac{1}{4}, \frac{1}{4}, z$ '.

### 2.2.14.2. Projections of centred cells (lattices)

For centred lattices, two different cases may occur:
(i) The projection direction is parallel to a lattice-centring vector. In this case, the projected plane cell is primitive for the centring types $A, B, C, I$ and $R$. For $F$ lattices, the multiplicity is reduced from 4 to 2 because $c$-centred plane cells result from projections along face diagonals of three-dimensional $F$ cells.

## Examples

(1) A body-centred lattice with centring vector $\frac{1}{2}(\mathbf{a}+\mathbf{b}+\mathbf{c})$ gives a primitive net, if projected along [111], [ $111 \overline{1}],[1 \overline{1} 1]$ or [11 $\overline{1}]$.
(2) A $C$-centred lattice projects to a primitive net along the directions [110] and [110].
(3) An $R$-centred lattice described with 'hexagonal axes' (triple cell) results in a primitive net, if projected along [111], [211] or [ $\overline{1} 21]$ for the obverse setting. For the reverse setting, the corresponding directions are [1 $\overline{1} 1],[\overline{2} \overline{1} 1],[121] ; c f$. Chapter 1.2.
(ii) The projection direction is not parallel to a lattice-centring vector (general projection direction). In this case, the plane cell has the same multiplicity as the three-dimensional cell. Usually, however, this centred plane cell is unconventional and a transformation is required to obtain the conventional plane cell. This transformation has been carried out for the projection data in this volume.

## Examples

(1) Projection along [010] of a cubic $I$-centred cell leads to an unconventional quadratic $c$-centred plane cell. A simple cell transformation leads to the conventional quadratic $p$ cell.
(2) Projection along [010] of an orthorhombic I-centred cell leads to a rectangular $c$-centred plane cell, which is conventional.
(3) Projection along [001] of an $R$-centred cell (both in obverse and reverse setting) results in a triple hexagonal plane cell $h$ (the two-dimensional analogue of the $H$ cell, $c f$. Chapter 1.2). A simple cell transformation leads to the conventional hexagonal $p$ cell.

### 2.2.14.3. Projections of symmetry elements

A symmetry element of a space group does not project as a symmetry element unless its orientation bears a special relation to the projection direction; all translation components of a symmetry

Table 2.2.14.2. Projections of crystallographic symmetry elements

| Symmetry element in three dimensions | Symmetry element in projection |
| :---: | :---: |
| Arbitrary orientation |  |
| $\left.\begin{array}{ll}\text { Symmetry centre } & \overline{1} \\ \text { Rotoinversion axis } & \overline{3} \equiv 3 \times \overline{1}\end{array}\right\}$ | Rotation point 2 (at projection of centre) |
| Parallel to projection direction |  |
| Rotation axis 2; 3; 4; 6 <br> Screw axis $2_{1}$ $\begin{aligned} & 3_{1}, 3_{2} \\ & 4_{1}, 4_{2}, 4_{3} \\ & 6_{1}, 6_{2}, 6_{3}, 6_{4}, 6_{5} \end{aligned}$ <br> Rotoinversion axis $\overline{4}$ $\begin{aligned} & \overline{6} \equiv 3 / m \\ & \overline{3} \equiv 3 \times \overline{1} \end{aligned}$ <br> Reflection plane $m$ <br> Glide plane with $\perp$ component* <br> Glide plane without $\perp$ component* | Rotation point 2; 3; 4; 6 <br> Rotation point 2 <br> 3 <br> 4 <br> 6 <br> Rotation point 4 <br> 3 , with overlap of atoms <br> 6 <br> Reflection line $m$ <br> Glide line $g$ <br> Reflection line $m$ |
| Normal to projection direction |  |
| Rotation axis 2; 4; 6 <br> 3 <br> Screw axis $4_{2} ; 6_{2}, 6_{4}$ $\begin{aligned} & 2_{1} ; 4_{1}, 4_{3} ; 6_{1}, 6_{3}, 6_{5} \\ & 3_{1}, 3_{2} \end{aligned}$ <br> Rotoinversion axis $\overline{4}$ $\begin{aligned} & \overline{6} \equiv 3 / m \\ & \overline{3} \equiv 3 \times \overline{1} \end{aligned}$ <br> Reflection plane $m$ <br> Glide plane with glide vector $\mathbf{t}$ | Reflection line $m$ <br> None <br> Reflection line $m$ <br> Glide line $g$ <br> None <br> Reflection line $m$ parallel to axis <br> Reflection line $m$ perpendicular to axis (through projection of inversion point) <br> Rotation point 2 (at projection of centre) <br> None, but overlap of atoms <br> Translation with translation vector $\mathbf{t}$ |

* The term 'with $\perp$ component' refers to the component of the glide vector normal to the projection direction.
operation along the projection direction vanish, whereas those perpendicular to the projection direction (i.e. parallel to the plane of projection) may be retained. This is summarized in Table 2.2.14.2 for the various crystallographic symmetry elements. From this table the following conclusions can be drawn:
(i) $n$-fold rotation axes and $n$-fold screw axes, as well as rotoinversion axes $\overline{4}$, parallel to the projection direction project as $n$-fold rotation points; a $\overline{3}$ axis projects as a sixfold, a $\overline{6}$ axis as a threefold rotation point. For the latter, a doubling of the projected electron density occurs owing to the mirror plane normal to the projection direction ( $\overline{6} \equiv 3 / \mathrm{m}$ ).
(ii) $n$-fold rotation axes and $n$-fold screw axes normal to the projection direction (i.e. parallel to the plane of projection) do not project as symmetry elements if $n$ is odd. If $n$ is even, all rotation and rotoinversion axes project as mirror lines: the same applies to the screw axes $4_{2}, 6_{2}$ and $6_{4}$ because they contain an axis 2 . Screw axes $2_{1}, 4_{1}, 4_{3}, 6_{1}, 6_{3}$ and $6_{5}$ project as glide lines because they contain $2_{1}$.
(iii) Reflection planes normal to the projection direction do not project as symmetry elements but lead to a doubling of the projected electron density owing to overlap of atoms. Projection of a glide plane results in an additional translation; the new translation vector

