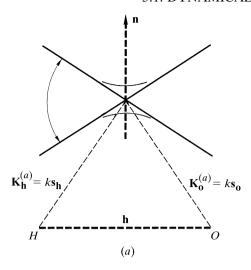
5.1. DYNAMICAL THEORY OF X-RAY DIFFRACTION



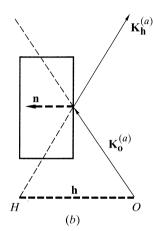


Fig. 5.1.3.3. Reflection, or Bragg, geometry. (a) Reciprocal space; (b) direct space.

$$\gamma_o = \cos(\mathbf{n}, \mathbf{s_o}); \quad \gamma_h = \cos(\mathbf{n}, \mathbf{s_h}).$$
 (5.1.3.2)

It will be noted that they are both positive, as is their ratio,

$$\gamma = \gamma_h / \gamma_o. \tag{5.1.3.3}$$

This is the *asymmetry ratio*, which is very important since the width of the rocking curve is proportional to its square root [equation (5.1.3.6)].

(b) Reflection, or Bragg case (Fig. 5.1.3.3). In this case there are three possible situations: the normal to the crystal surface drawn from M intersects either branch 1 or branch 2 of the dispersion surface, or the intersection points are imaginary (Fig. 5.1.3.3a). The reflected wave is directed towards the *outside* of the crystal (Fig. 5.1.3.3b). The cosines defined by (5.1.3.2) are now positive for γ_0 and negative for γ_h . The asymmetry factor is therefore also negative.

5.1.3.3. Middle of the reflection domain

It will be apparent from the equations given later that the incident wavevector corresponding to the middle of the reflection domain is, in both cases, **OI**, where *I* is the intersection of the normal to the crystal surface drawn from the Lorentz point, L_o , with T_o' (Figs. 5.1.3.4 and 5.1.3.5), while, according to Bragg's law, it should be \mathbf{OL}_a . The angle $\Delta\theta$ between the incident wavevectors \mathbf{OL}_a and \mathbf{OI} , corresponding to the middle of the reflecting domain according to the geometrical and dynamical theories, respectively, is

$$\Delta \theta_o = \overline{L_a I}/k = R\lambda^2 F_o(1 - \gamma)/(2\pi V \sin 2\theta). \tag{5.1.3.4}$$

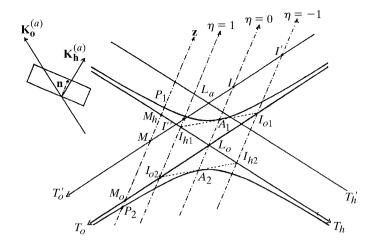


Fig. 5.1.3.4. Boundary conditions at the entrance surface for transmission geometry.

In the Bragg case, the asymmetry ratio γ is negative and $\Delta\theta_o$ is never equal to zero. This difference in Bragg angle between the two theories is due to the refraction effect, which is neglected in geometrical theory. In the Laue case, $\Delta\theta_o$ is equal to zero for symmetric reflections ($\gamma = 1$).

5.1.3.4. Deviation parameter

The solutions of dynamical theory are best described by introducing a reduced parameter called the *deviation parameter*,

$$\eta = (\Delta \theta - \Delta \theta_o)/\delta, \tag{5.1.3.5}$$

where

$$\delta = R\lambda^2 |C| (|\gamma| F_h F_{\bar{h}})^{1/2} / (\pi V \sin 2\theta), \tag{5.1.3.6}$$

whose real part is equal to the half width of the rocking curve (Sections 5.1.6 and 5.1.7). The width 2δ of the rocking curve is sometimes called the *Darwin width*.

The definition (5.1.3.5) of the deviation parameter is independent of the geometrical situation (reflection or transmission case); this is not followed by some authors. The present convention has the advantage of being quite general.

In an absorbing crystal, η , $\Delta\theta_o$ and δ are complex, and it is the real part, $\Delta\theta_{or}$, of $\Delta\theta_o$ which has the geometrical interpretation given in Section 5.1.3.3. One obtains

$$\eta = \eta_r + i\eta_i
\eta_r = (\Delta\theta - \Delta\theta_{or})/\delta_r; \ \eta_i = A\eta_r + B
A = -\tan\beta
B = \left\{ \chi_{io} / \left[|C| (|\chi_h \chi_{\bar{h}}|)^{1/2} \cos\beta \right] \right\} (1 - \gamma)/2 (|\gamma|)^{1/2},$$
(5.1.3.7)

where β is the phase angle of $(\chi_h \chi_{\bar{h}})^{1/2}$ [or that of $(F_h F_{\bar{h}})^{1/2}$].

5.1.3.5. Pendellösung and extinction distances

Let

$$\Lambda_{o} = \pi V(\gamma_{o}|\gamma_{h}|)^{1/2} / [R\lambda|C|(F_{h}F_{\bar{h}})^{1/2}]. \tag{5.1.3.8}$$

This length plays a very important role in the dynamical theory of diffraction by both perfect and deformed crystals. For example, it is 15.3 μ m for the 220 reflection of silicon, with Mo $K\alpha$ radiation and a symmetric reflection.

In *transmission* geometry, it gives the period of the interference between the two excited wavefields which constitutes the *Pendellösung* effect first described by Ewald (1917) (see Section

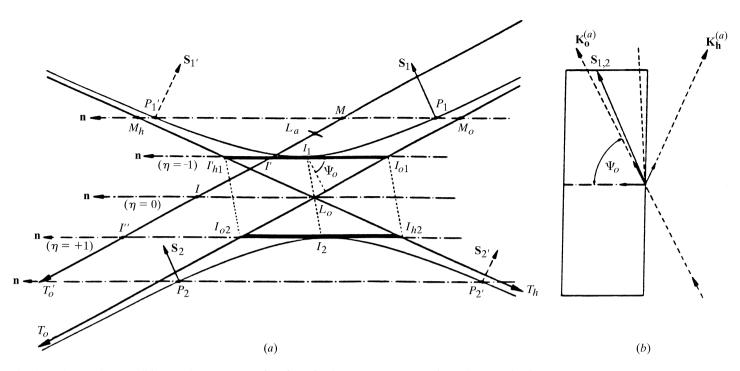


Fig. 5.1.3.5. Boundary conditions at the entrance surface for reflection geometry. (a) Reciprocal space; (b) direct space.

5.1.6.3); Λ_o in this case is called the *Pendellösung distance*, denoted Λ_L hereafter. Its geometrical interpretation, in the zero-absorption case, is the inverse of the diameter A_2A_1 of the dispersion surface in a direction defined by the cosines γ_h and γ_o with respect to the reflected and incident directions, respectively (Fig. 5.1.3.4). It reduces to the inverse of $A_{o2}A_{o1}$ (5.1.2.23) in the symmetric case.

In reflection geometry, it gives the absorption distance in the total-reflection domain and is called the *extinction* distance, denoted Λ_B (see Section 5.1.7.1). Its geometrical interpretation in the zero-absorption case is the inverse of the length $I_{o1}I_{h1} = I_{h2}I_{o2}$, Fig. 5.1.3.5.

In a *deformed* crystal, if distortions are of the order of the width of the rocking curve over a distance Λ_o , the crystal is considered to be slightly deformed, and ray theory (Penning & Polder, 1961; Kato, 1963, 1964*a,b*) can be used to describe the propagation of wavefields. If the distortions are larger, new wavefields may be generated by interbranch scattering (Authier & Balibar, 1970) and generalized dynamical diffraction theory such as that developed by Takagi (1962, 1969) should be used.

Using (5.1.3.8), expressions (5.1.3.5) and (5.1.3.6) can be rewritten in the very useful form:

$$\eta = (\Delta \theta - \Delta \theta_o) \Lambda_o \sin 2\theta / (\lambda | \gamma_h |),
\delta = \lambda | \gamma_h | / (\Lambda_o \sin 2\theta).$$
(5.1.3.9)

The order of magnitude of the Darwin width 2δ ranges from a fraction of a second of an arc to ten or more seconds, and increases with increasing wavelength and increasing structure factor. For example, for the 220 reflection of silicon and Cu $K\alpha$ radiation, it is 5.2 seconds.

5.1.3.6. Solution of the dynamical theory

The coordinates of the tie points excited by the incident wave are obtained by looking for the intersection of the dispersion surface, (5.1.2.22), with the normal Mz to the crystal surface (Figs. 5.1.3.4 and 5.1.3.5). The ratio ξ of the amplitudes of the waves of the

corresponding wavefields is related to these coordinates by (5.1.2.24) and is found to be

$$\xi_{j} = D_{hj}/D_{oj}
= -S(C)S(\gamma_{h})[(F_{h}F_{\bar{h}})^{1/2}/F_{\bar{h}}]
\times \left\{ \eta \pm \left[\eta^{2} + S(\gamma_{h}) \right]^{1/2} \right\} / (|\gamma|)^{1/2},$$
(5.1.3.10)

where the plus sign corresponds to a tie point on branch 1 (j = 1) and the minus sign to a tie point on branch 2 (j = 2), and $S(\gamma_h)$ is the sign of γ_h (+1 in transmission geometry, -1 in reflection geometry).

5.1.3.7. Geometrical interpretation of the solution in the zero-absorption case

5.1.3.7.1. Transmission geometry

In this case (Fig. 5.1.3.4) $S(\gamma_h)$ is +1 and (5.1.3.10) may be written

$$\xi_j = -S(C) \left[\eta \pm (\eta^2 + 1)^{1/2} \right] / \gamma^{1/2}.$$
 (5.1.3.11)

Let A_1 and A_2 be the intersections of the normal to the crystal surface drawn from the Lorentz point L_o with the two branches of the dispersion surface (Fig. 5.1.3.4). From Sections 5.1.3.3 and 5.1.3.4, they are the tie points excited for $\eta=0$ and correspond to the middle of the reflection domain. Let us further consider the tangents to the dispersion surface at A_1 and A_2 and let I_{o1} , I_{o2} and I_{h1} , I_{h2} be their intersections with I_o and I_h , respectively. It can be shown that $\overline{I_{o1}I_{h2}}$ and $\overline{I_{o2}I_{h1}}$ intersect the dispersion surface at the tie points excited for $\eta=-1$ and $\eta=+1$, respectively, and that the $Pendell\ddot{o}sung$ distance $A_L=1/A_2A_1$, the width of the rocking curve $2\delta=\overline{I_{o1}I_{o2}}/k$ and the deviation parameter $\eta=\overline{M_oM_h}/A_2A_1$, where I_o and I_o are the intersections of the normal to the crystal surface drawn from the extremity of any incident wavevector I_o with I_o and I_o , respectively.