List of symbols and abbreviations used in this volume

(1) Points and point space		(4) Groups	
P, Q, R	points	${\cal G}$	group; space group
0	origin	${\cal R}$	space group (Chapter 1.5)
A_n , \mathbb{A}_n , P_n	<i>n</i> -dimensional affine space	\mathcal{H},\mathcal{U}	subgroups of \mathcal{G}
E_n, \mathbb{E}_n	<i>n</i> -dimensional Euclidean point space	\mathcal{M}	maximal subgroup of \mathcal{G} (Chapter 1.5)
x, y, z ; or x_i	point coordinates	\mathcal{M}	Hermann's group (Chapter 1.2)
x	column of point coordinates	$\mathcal{P},\mathcal{S},\mathcal{V},\mathcal{Z}$	groups
$ ilde{X}$	image point	$\mathcal{T}(\mathcal{G}),\mathcal{T}(\mathcal{R})$	group of all translations of \mathcal{G} , \mathcal{R}
\tilde{x}	column of coordinates of an image point	\mathcal{A}	group of all affine mappings = affine group
$ ilde{x}_i$	coordinates of an image point	${\cal E}$	group of all isometries (motions)
$x^{'}$	column of coordinates in a new coordinate		= Euclidean group
	system (after basis transformation)	${\mathcal F}$	factor group
x_i'	coordinates in a new coordinate system	${\cal I}$	trivial group, consisting of the unit element
•			e only
		$\mathcal N$	normal subgroup
(2) Vectors and vector space		\mathcal{O}	group of all orthogonal mappings
$\mathbf{a}, \mathbf{b}, \mathbf{c}; \text{ or } \mathbf{a}_i$	basis vectors of the space		= orthogonal group
\mathbf{r}, \mathbf{x}	vectors, position vectors	$\mathcal{N}_{\mathcal{G}}(\mathcal{H})$	normalizer of $\mathcal H$ in $\mathcal G$
0	zero vector (all coefficients zero)	$\mathcal{N}_{\mathcal{E}}(\mathcal{H})$	Euclidean normalizer of ${\cal H}$
a, b, c	lengths of basis vectors \ lattice	$\mathcal{N}_{\mathcal{A}}(\mathcal{H})$	affine normalizer of ${\cal H}$
α, β, γ ; or α_j	angles between basis vectors \(\) parameters	$\mathcal{P}_{\mathcal{G}}, \mathcal{P}_{\mathcal{H}}$	point groups of the space groups \mathcal{G}, \mathcal{H}
$r \\ r_i$	column of vector coefficients vector coefficients	$\mathcal{S}_{\mathcal{G}}(X), \mathcal{S}_{\mathcal{H}}(X)$	site-symmetry groups of point X in the space groups \mathcal{G} , \mathcal{H}
$(\mathbf{a})^{\mathrm{T}}$	row of basis vectors	a, b, g, h, m, t	group elements
\mathbf{V}_n	<i>n</i> -dimensional vector space	e	unit element
'n	, difference space	i or $[i]$	index of ${\mathcal H}$ in ${\mathcal G}$
(3) Mappings and their matrices and columns		(5) Symbols used in the tables	
A, W	(3×3) matrices	p	prime number
$m{A}^{ ext{T}}$	matrix A transposed	n, n'	arbitrary positive integer numbers
I	(3×3) unit matrix	q, r, u, v, w	arbitrary integer numbers in the given range
A_{ik}, W_{ik}	matrix coefficients	a, b, c	basis vectors of the space group
(A,a),(W,w)	matrix-column pairs	$\mathbf{a}',\mathbf{b}',\mathbf{c}'$	basis vectors of the subgroup or supergroup
W	augmented matrix	x, y, z	site coordinates in the space group
x, x, t	augmented columns	t(1,0,0),	generating translations
P , ₽	transformation matrices	$t(0,1,0),\ldots$	
A, I, W	mappings	(C) All	
w	column of the translation part of a	(6) Abbreviation	
	mapping	HM symbol	Hermann–Mauguin symbol
W_{i}	coefficients of the translation part of a mapping	IT A	International Tables for Crystallography Volume A
G, G_{ik}	fundamental matrix and its coefficients	PCA	parent-clamping approximation
$\det(\ldots)$	determinant of a matrix	k-subgroup	klassengleiche subgroup
tr()	trace of a matrix	<i>t</i> -subgroup	translationengleiche subgroup