

4. SYNOPTIC TABLES OF SPACE-GROUP SYMBOLS

Table 4.3.2.1. Index of symbols for space groups for various settings and cells (cont.)

TRIGONAL SYSTEM

No. of space group	Schoenflies symbol	Hermann-Mauguin symbols for standard cell <i>P</i> or <i>R</i>			Triple cell <i>H</i>
		Short	Full	Extended	
143	C_3^1	$P3$			$H3$
144	C_3^2	$P3_1$			$H3_1$
145	C_3^3	$P3_2$			$H3_2$
146	C_3^4	$R3$		$R3$ $3_{1,2}$	
147	C_{3i}^1	$P\bar{3}$			$H\bar{3}$
148	C_{3i}^2	$R\bar{3}$		$R\bar{3}$ $3_{1,2}$	
149	D_3^1	$P312$		$P312$ 2_1	$H321$
150	D_3^2	$P321$		$P321$ 2_1	$H312$
151	D_3^3	$P3_112$		$P3_112$ 2_1	$H3_121$
152	D_3^4	$P3_121$		$P3_121$ 2_1	$H3_112$
153	D_3^5	$P3_212$		$P3_212$ 2_1	$H3_221$
154	D_3^6	$P3_221$		$P3_221$ 2_1	$H3_212$
155	D_3^7	$R32$		$R3$ 2 $3_{1,2}2_1$	
156	C_{3v}^1	$P3m1$		$P3m1$ b	$H31m$
157	C_{3v}^2	$P31m$		$P31m$ a	$H3m1$
158	C_{3v}^3	$P3c1$		$P3c1$ n	$H31c$
159	C_{3v}^4	$P31c$		$P31c$ n	$H3c1$
160	C_{3v}^5	$R3m$		$R3$ m $3_{1,2}b$	
161	C_{3v}^6	$R3c$		$R3$ c $3_{1,2}n$	
162	D_{3d}^1	$P\bar{3}1m$	$P\bar{3}12/m$	$P\bar{3}12/m$ $2_1/a$	$H\bar{3}m1$
163	D_{3d}^2	$P\bar{3}1c$	$P\bar{3}12/c$	$P\bar{3}12/c$ $2_1/n$	$H\bar{3}c1$
164	D_{3d}^3	$P\bar{3}m1$	$P\bar{3}2/m1$	$P\bar{3}2/m1$ $2_1/b$	$H\bar{3}1m$
165	D_{3d}^4	$P\bar{3}c1$	$P\bar{3}2/c1$	$P\bar{3}2/c1$ $2_1/n$	$H\bar{3}1c$
166	D_{3d}^5	$R\bar{3}m$	$R\bar{3}2/m$	$R\bar{3}$ $2/m$ $3_{1,2}2_1/b$	
167	D_{3d}^6	$R\bar{3}c$	$R\bar{3}2/c$	$R\bar{3}$ $2/c$ $3_{1,2}2_1/n$	

HEXAGONAL SYSTEM

No. of space group	Schoenflies symbol	Hermann-Mauguin symbols for standard cell <i>P</i>			Triple cell <i>H</i>
		Short	Full	Extended	
168	C_6^1	$P6$			$H6$
169	C_6^2	$P6_1$			$H6_1$
170	C_6^3	$P6_5$			$H6_5$
171	C_6^4	$P6_2$			$H6_2$
172	C_6^5	$P6_4$			$H6_4$
173	C_6^6	$P6_3$			$H6_3$
174	C_{3h}^1	$P\bar{6}$			$H\bar{6}$
175	C_{6h}^1	$P6/m$			$H6/m$
176	C_{6h}^2	$P6_3/m$			$H6_3/m$
177	D_6^1	$P622$		$P62$ 2 2_12_1	$H622$
178	D_6^2	$P6_122$		$P6_12$ 2 2_12_1	$H6_122$
179	D_6^3	$P6_522$		$P6_52$ 2 2_12_1	$H6_522$
180	D_6^4	$P6_222$		$P6_22$ 2 2_12_1	$H6_222$
181	D_6^5	$P6_422$		$P6_42$ 2 2_12_1	$H6_422$
182	D_6^6	$P6_322$		$P6_32$ 2 2_12_1	$H6_322$
183	C_{6v}^1	$P6mm$		$P6mm$ ba	$H6mm$
184	C_{6v}^2	$P6cc$		$P6cc$ nn	$H6cc$
185	C_{6v}^3	$P6_3cm$		$P6_3cm$ na	$H6_3mc$
186	C_{6v}^4	$P6_3mc$		$P6_3mc$ bn	$H6_3cm$
187	D_{3h}^1	$P\bar{6}m2$		$P\bar{6}m2$ $b2_1$	$H\bar{6}2m$
188	D_{3h}^2	$P\bar{6}c2$		$P\bar{6}c2$ $n2_1$	$H\bar{6}2c$
189	D_{3h}^3	$P\bar{6}2m$		$P\bar{6}2m$ 2_1a	$H\bar{6}m2$
190	D_{3h}^4	$P\bar{6}2c$		$P\bar{6}2$ c 2_1n	$H\bar{6}c2$
191	D_{6h}^1	$P6/mmm$	$P6/m2/m2/m$	$P6/m$ $2/m$ $2/m$ $2_1/b$ $2_1/a$	$H6/mmm$
192	D_{6h}^2	$P6/mcc$	$P6/m2/c2/c$	$P6/m$ $2/c$ $2/c$ $2_1/n$ $2_1/n$	$H6/mcc$
193	D_{6h}^3	$P6_3/mcm$	$P6_3/m2/c2/m$	$P6_3/m$ $2/c$ $2/m$ $2_1/b$ $2_1/a$	$H6_3/mmc$
194	D_{6h}^4	$P6_3/mmc$	$P6_3/m2/m2/c$	$P6_3/m$ $2/m$ $2/c$ $2_1/b$ $2_1/n$	$H6_3/mcm$

Example: $B 2/b 11$ (15, unique axis a)

$2_1/n$

The t subgroups of index [2] (type **I**) are $B211(C2)$; $Bb11(Cc)$; $B\bar{1}(P\bar{1})$.

The k subgroups of index [2] (type **IIa**) are $P2/b11(P2/c)$; $P2_1/b11(P2_1/c)$; $P2/n11(P2/c)$; $P2_1/n11(P2_1/c)$.

Some subgroups of index [4] (not maximal) are $P211(P2)$; $P2_11(P2_1)$; $Pb11(Pc)$; $Pn11(Pc)$; $P\bar{1}$; $B1(P1)$.

4.3.3. Orthorhombic system

4.3.3.1. Historical note and arrangement of the tables

The synoptic table of *IT* (1935) contained space-group symbols for the six orthorhombic ‘settings’, corresponding to the six permutations of the basis vectors **a**, **b**, **c**. In *IT* (1952), left-handed systems like $\bar{c}ba$ were changed to right-handed systems by reversing the orientation of the c axis, as in **cba**. Note that reversal

4.3. SYMBOLS FOR SPACE GROUPS

Table 4.3.2.1. Index of symbols for space groups for various settings and cells (cont.)

CUBIC SYSTEM

No. of space group	Schoenflies symbol	Hermann–Mauguin symbols		
		Short	Full	Extended†
195	T^1	$P23$		
196	T^2	$F23$		$F23$ 2 2 ₁ 2 ₁
197	T^3	$I23$		$I23$ 2 ₁
198	T^4	$P2_13$		
199	T^5	$I2_13$		$I2_13$ 2
200	T_h^1	$Pm\bar{3}$	$P2/m\bar{3}$	
201	T_h^2	$Pn\bar{3}$	$P2/n\bar{3}$	
202	T_h^3	$Fm\bar{3}$	$F/2m\bar{3}$	$F2/m\bar{3}$ 2/n 2 ₁ /e 2 ₁ /e
203	T_h^4	$Fd\bar{3}$	$F2/d\bar{3}$	$F2/d\bar{3}$ 2/d 2 ₁ /d 2 ₁ /d
204	T_h^5	$Im\bar{3}$	$I2/m\bar{3}$	$I2/m\bar{3}$ 2 ₁ /n
205	T_h^6	$Pa\bar{3}$	$P2_1/a\bar{3}$	
206	T_h^7	$Ia\bar{3}$	$I2_1/a\bar{3}$	$I2_1/a\bar{3}$ 2/b
207	O^1	$P432$		$P4\ 32$ 2 ₁
208	O^2	$P4_232$		$P4_232$ 2 ₁
209	O^3	$F432$		$F4\ 32$ 4 2 4 ₂ 2 ₁ 4 ₂ 2 ₁
210	O^4	$F4_132$		$F4_132$ 4 ₁ 2 4 ₃ 2 ₁ 4 ₃ 2 ₁
211	O^5	$I432$		$I4\ 32$ 4 ₂ 2 ₁
212	O^6	$P4_332$		$P4_3\ 32$ 2 ₁
213	O^7	$P4_132$		$P4_132$ 2 ₁
214	O^8	$I4_132$		$I4_132$ 4 ₃ 2 ₁

CUBIC SYSTEM (cont.)

No. of space group	Schoenflies symbol	Hermann–Mauguin symbols		
		Short	Full	Extended†
215	T_d^1	$P\bar{4}3m$		$P\bar{4}3m$
216	T_d^2	$F\bar{4}3m$		$F\bar{4}3m$ g g g ₂ g ₂
217	T_d^3	$I\bar{4}3m$		$I\bar{4}3m$ e
218	T_d^4	$P\bar{4}3n$		$P\bar{4}3n$ c
219	T_d^5	$F\bar{4}3c$		$F\bar{4}3n$ c g ₁ g ₁
220	T_d^6	$I\bar{4}3d$		$I\bar{4}3d$ d
221	O_h^1	$Pm\bar{3}m$	$P4/m\bar{3}2/m$	$P4/m\bar{3}2/m$ 2 ₁ /g
222	O_h^2	$Pn\bar{3}n$	$P4/n\bar{3}2/n$	$P4/n\bar{3}2/n$ 2 ₁ /c
223	O_h^3	$Pm\bar{3}n$	$P4_2/m\bar{3}2/n$	$P4_2/m\bar{3}2/n$ 2 ₁ /c
224	O_h^4	$Pn\bar{3}m$	$P4_2/n\bar{3}2/m$	$P4_2/n\bar{3}2/m$ 2 ₁ /g
225	O_h^5	$Fm\bar{3}m$	$F4/m\bar{3}2/m$	$F4/m\ \bar{3}2/m$ 4/n 2/g 4 ₂ /e 2 ₁ /g ₂ 4 ₂ /e 2 ₁ /g ₂
226	O_h^6	$Fm\bar{3}c$	$F4/m\bar{3}2/c$	$F4/m\bar{3}2/n$ 4/n 2/c 4 ₂ /e 2 ₁ /g ₁ 4 ₂ /e 2 ₁ /g ₁
227	O_h^7	$Fd\bar{3}m$	$F4_1/d\bar{3}2/m$	$F4_1/d\bar{3}2/m$ 4 ₁ /d 2/g 4 ₃ /d 2 ₁ /g ₂ 4 ₃ /d 2 ₁ /g ₂
228	O_h^8	$Fd\bar{3}c$	$F4_1/d\bar{3}2/c$	$F4_1/d\bar{3}2/n$ 4 ₁ /d 2/c 4 ₃ /d 2 ₁ /g ₁ 4 ₃ /d 2 ₁ /g ₁
229	O_h^9	$Im\bar{3}m$	$I4/m\bar{3}2/m$	$I4/m\bar{3}2/m$ 4 ₂ /n 2 ₁ /e
230	O_h^{10}	$Ia\bar{3}d$	$I4_1/a\bar{3}2/d$	$I4_1/a\bar{3}2/d$ 4 ₃ /b 2 ₁ /d

† Axes 3₁ and 3₂ parallel to axes 3 are not indicated in the extended symbols: cf. Chapter 4.1. For the glide-plane symbol 'e', see the *Foreword to the Fourth Edition* (IT 1995) and Section 1.3.2, Note (x).

Note: The glide planes g , g_1 and g_2 have the glide components $g(\frac{1}{2}, \frac{1}{2}, 0)$, $g_1(\frac{1}{4}, \frac{1}{4}, 0)$ and $g_2(\frac{1}{4}, \frac{1}{4}, \frac{1}{2})$.

of two axes does not change the handedness of a coordinate system, so that the settings $\bar{c}ba$, $c\bar{b}a$, $cb\bar{a}$ and $\bar{c}\bar{b}\bar{a}$ are equivalent in this respect. The tabulation thus deals with the $6 \times 4 = 24$ possible right-handed settings. For further details see Section 2.2.6.4.

An important innovation of *IT* (1952) was the introduction of extended symbols for the centred groups A , B , C , I , F . These

symbols are systematically developed in Table 4.3.2.1. Settings which permute the two axes \mathbf{a} and \mathbf{b} are listed side by side so that the two C settings appear together, followed by the two A and the two B settings.

In crystal classes $mm2$ and 222 , the last symmetry element is the product of the first two and thus is not independent. It was omitted in

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the short Hermann–Mauguin symbols of *IT* (1935) for all space groups of class *mm2*, but was restored in *IT* (1952). In space groups of class 222, the last symmetry element cannot be omitted (see examples below).

For the new ‘double’ glide plane symbol ‘*e*’, see the *Foreword to the Fourth Edition* (*IT* 1995) and Section 1.3.2, Note (x).

4.3.3.2. Group–subgroup relations

The present section emphasizes the use of the extended and full symbols for the derivation of maximal subgroups of types **I** and **IIa**; maximal orthorhombic subgroups of types **IIb** and **IIc** cannot be recognized by inspection of the synoptic Table 4.3.2.1.

4.3.3.2.1. Maximal non-isomorphic *k* subgroups of type **IIa** (decentred)

(i) Extended symbols of centred groups *A*, *B*, *C*, *I*

By convention, the second line of the extended space-group symbol is the result of the multiplication of the first line by the centring translation (cf. Table 4.1.2.3). As a consequence, the product of any two terms in one line is equal to the product of the corresponding two terms in the other line.

(a) Class 222

The extended symbol of *I222* (23) is $I2\ 2\ 2$; the twofold axes $2_1 2_1 2_1$

intersect and one obtains $2_x \times 2_y = 2_z = 2_{1x} \times 2_{1y}$.

Maximal *k* subgroups are *P222* and $P2_1 2_1 2$ (plus permutations) but not $P2_1 2_1 2_1$.

The extended symbol of $I2_1 2_1 2_1$ (24) is $I2_1 2_1 2_1$, where one $2\ 2\ 2$

obtains $2_{1x} \times 2_{1y} = 2_{1z} = 2_x \times 2_y$; the twofold axes do not intersect. Thus, maximal non-isomorphic *k* subgroups are $P2_1 2_1 2_1$ and $P222_1$ (plus permutations), but not *P222*.

(b) Class *mm2*

The extended symbol of *Aea2* (41) is $Aba2$; the following $cn2_1$

relations hold: $b \times a = 2 = c \times n$ and $b \times n = 2_1 = c \times a$.

Maximal *k* subgroups are *Pba2*; *Pcn2* (*Pnc2*); *Pbn2*₁ (*Pna2*₁); *Pca2*₁.

(c) Class *mmm*

By convention, the first line of the extended symbol contains those symmetry elements for which the coordinate triplets are explicitly printed under *Positions*. From the two-line symbols, as defined in the example below, one reads not only the eight maximal *k* subgroups *P* of class *mmm* but also the location of their centres of symmetry, by applying the following rules:

If in the symbol of the *P* subgroup the number of symmetry planes, chosen from the first line of the extended symbol, is odd (three or one), the symmetry centre is at 0, 0, 0; if it is even (two or zero), the symmetry centre is at $\frac{1}{4}, \frac{1}{4}, 0$ for the subgroups of *C* groups and at $\frac{1}{4}, \frac{1}{4}, \frac{1}{4}$ for the subgroups of *I* groups (Bertaut, 1976).

Examples

(1) According to these rules, the extended symbol of *Cmce* (64) is $Cmcb$ (see above). The four *k* subgroups with symmetry centres

bna

at 0, 0, 0 are *Pmcb* (*Pbam*); *Pmna*; *Pbca*; *Pbnb* (*Pccn*); those with symmetry centres at $\frac{1}{4}, \frac{1}{4}, 0$ are *Pbna* (*Pbcn*); *Pmca*

(*Pbcm*); *Pmnb* (*Pnma*); *Pbcb* (*Pcca*). These rules can easily be transposed to other settings.

(2) The extended symbol of *Ibam* (72) is $Ibam$. The four subgroups ccn

with symmetry centre at 0, 0, 0 are *Pbam*; *Pbcn*; *Pcan* (*Pbcn*); *Pccm*;

those with symmetry centre at $\frac{1}{4}, \frac{1}{4}, \frac{1}{4}$ are *Pccn*; *Pcam* (*Pbcm*); *Pbcm*; *Pban*.

(ii) Extended symbols of *F*-centred space groups

Maximal *k* subgroups of the groups *F222*, *Fmm2* and *Fmmm* are *C*, *A* and *B* groups. The corresponding centring translations are $w = t(\frac{1}{2}, \frac{1}{2}, 0)$, $u = t(0, \frac{1}{2}, \frac{1}{2})$ and $v = w \times u = t(\frac{1}{2}, 0, \frac{1}{2})$.

The (four-line) extended symbols of these groups can be obtained from the following scheme:

	<i>F222</i> (22)	<i>Fmm2</i> (42)	<i>Fmmm</i> (69)
1	222	<i>mm2</i>	<i>mmm</i>
<i>w</i>	$2_1 2_1 2^w$	$ba2^w$	<i>ban</i>
<i>u</i>	$2^u 2_1^u 2_1$	$nc2_1$	<i>ncb</i>
<i>v</i>	$2_1^u 2^v 2_1^w$	$cn2_1^w$	<i>cna</i>

The second, third, and fourth lines are the result of the multiplication of the first line by the centring translations *w*, *u* and *v*, respectively.

The following abbreviations are used:

$$2_z^w = w \times 2_z; \quad 2_{1z}^w = w \times 2_{1z}; \quad \text{etc.}$$

For the location of the symmetry elements in the above scheme, see Table 4.1.2.3. In Table 4.3.2.1, the centring translations and the superscripts *u*, *v*, *w* have been omitted. The first two lines of the scheme represent the extended symbols of *C222*, *Cmm2* and *Cmmm*. An interchange of the symmetry elements in the first two lines does not change the group. To obtain further maximal *C* subgroups, one has to replace symmetry elements of the first line by corresponding elements of the third or fourth line. Note that the symbol ‘*e*’ is not used in the four-line symbols for *Fmm2* and *Fmmm* in order to keep the above scheme transparent.

Examples

(1) *F222* (22). In the first line replace 2_x by 2_x^u (third line, same column) and keep 2_y . Complete the first line by the product $2_x^u \times 2_y = 2_{1z}$ and obtain the maximal *C* subgroup $C2^u 2_1$.

Similarly, in the first line keep 2_x and replace 2_y with 2_y^v (fourth line, same column). Complete the first line by the product $2_x \times 2_y^v = 2_{1z}$ and obtain the maximal *C* subgroup $C2^v 2_1$.

Finally, replace 2_x and 2_y by 2_x^u and 2_y^v and form the product $2_x^u \times 2_y^v = 2_z^w$, to obtain the maximal *C* subgroup $C2^u 2^v 2^w$ (where 2^w can be replaced by 2). Note that $C222$ and $C2^u 2^v 2^w$ are two different subgroups, as are $C2^u 2_1$ and $C2^v 2_1$.

(2) *Fmm2* (42). A similar procedure leads to the four maximal *k* subgroups *Cmm2*; $Cmc2_1$; $Ccm2_1^w$ ($Cmc2_1$); and *Ccc2*.

(3) *Fmmm* (69). One finds successively the eight maximal *k* subgroups *Cmmm*; *Cmma*; *Cmcm*; *Ccmm* (*Cmcm*); *Cmca*; *Ccma* (*Cmca*); *Cccm*; and *Ccca*.

Maximal *A*- and *B*-centred subgroups can be obtained from the *C* subgroups by simple symmetry arguments.

In space groups *Fdd2* (43) and *Fddd* (70), the nature of the *d* planes is not altered by the translations of the *F* lattice; for this reason, a two-line symbol for *Fdd2* and a one-line symbol for *Fddd* are sufficient. There exist no maximal non-isomorphic *k* subgroups for these two groups.