

## 18. REFINEMENT

## 18.5.6. The diffraction-component precision index

## 18.5.6.1. Statistical expectation of error dependence

From general statistical theory, one would expect the s.u. of an atomic coordinate determined from the diffraction data alone to show dependence on four factors:

$$\sigma(x) \propto (\mathcal{R})[(n_{\text{atoms}})/(n_{\text{obs}} - n_{\text{params}})]^{1/2}(1/s_{\text{rms}}). \quad (18.5.6.1)$$

Here,  $\mathcal{R}$  is some measure of the precision of the data;  $n_{\text{atoms}}$  is the recognition that the information content of the data has to be shared out;  $n_{\text{obs}}$  is the number of independent data, but to achieve the correct number of degrees of freedom this must be reduced by  $n_{\text{params}}$ , the number of parameters determined; and  $1/s_{\text{rms}}$  is a more specialized factor arising from the sensitivity  $\partial|F|/\partial x$  of the data to the parameter  $x$ . Here  $s_{\text{rms}}$  is the r.m.s. reciprocal radius of the data. Any statistical error estimate must show some correspondence to these four factors.

## 18.5.6.2. A simple error formula

Cruickshank (1960) offered a simple order-of-magnitude formula for  $\sigma(x)$  in small molecules. It was intended for use in experimental design: how many data of what precision are needed to achieve a given precision in the results? The formula, derived from a very rough estimate of a least-squares diagonal element in non-centrosymmetric space groups, was

$$\sigma(x_i) = (1/2)(N_i/p)^{1/2}[R/s_{\text{rms}}] \quad (18.5.6.2)$$

Here  $p = n_{\text{obs}} - n_{\text{params}}$ ,  $R$  is the usual residual  $\sum |\Delta F|/\sum |F|$  and  $N_i$  is the number of atoms of type  $i$  needed to give scattering power at  $s_{\text{rms}}$  equal to that of the asymmetric unit of the structure, i.e.,  $\sum_j f_j^2 \equiv N_i f_i^2$ . [The formula has also proved very useful in a systematic study of coordinate precision in the many thousands of small-molecule structure analyses recorded in the Cambridge Structural Database (Allen *et al.*, 1995a,b).]

For small molecules, the above definition of  $N_i$  allowed the treatment of different types of atom with not-too-different  $B$ 's. However, it is not suitable for individual atoms in proteins where there is a very large range of  $B$  values and some atoms have  $B$ 's so large as to possess negligible scattering power at  $s_{\text{rms}}$ .

Often, as in isotropic refinement,  $n_{\text{params}} \simeq 4n_{\text{atoms}}$ , where  $n_{\text{atoms}}$  is the total number of atoms in the asymmetric unit. For fully anisotropic refinement,  $n_{\text{params}} \simeq 9n_{\text{atoms}}$ .

A first very rough extension of (18.5.6.2) for application in proteins to an atom with  $B = B_i$  is

$$\sigma(x_i) = k(N_i/p)^{1/2}[g(B_i)/g(B_{\text{avg}})]C^{-1/3}Rd_{\text{min}}, \quad (18.5.6.3)$$

where  $k$  is about 1.0,  $N_i = \sum Z_j^2/Z_i^2$ ,  $B_{\text{avg}}$  is the average  $B$  for fully occupied sites and  $C$  is the fractional completeness of the data to  $d_{\text{min}}$ . In deriving (18.5.6.3) from (18.5.6.2),  $1/s_{\text{rms}}$  has been replaced by  $1.3d_{\text{min}}$ , and the factor  $(1/2)(1.3) = 0.65$  has been increased to 1.0 as a measure of caution in the replacement of a full matrix by a diagonal approximation.  $g(B) = 1 + a_1B + a_2B^2$  is an empirical function to allow for the dependence of  $\sigma(x)$  on  $B$ . However, the results in Section 18.5.4.2 showed that the parameters  $a_1$  and  $a_2$  depend on the structure.

As also mentioned in Section 18.5.4.2, Sheldrick has found that the  $Z_i$  in  $N_i$  is better replaced by  $Z_i^\#$ , the scattering factor at  $\sin \theta/\lambda = 0.3 \text{ \AA}^{-1}$ . Hence,  $N_i$  may be taken as

$$N_i = (\sum Z_j^{\#2}/Z_i^{\#2}). \quad (18.5.6.4)$$

A useful comparison of the relative precision of different structures may be obtained by comparing atoms with the respective  $B = B_{\text{avg}}$  in the different structures. (18.5.6.3) then reduces to

$$\sigma(x, B_{\text{avg}}) = 1.0(N_i/p)^{1/2}C^{-1/3}Rd_{\text{min}}. \quad (18.5.6.5)$$

The smaller the  $d_{\text{min}}$  and the  $R$ , the better the precision of the structure. If the difference between oxygen, nitrogen and carbon atoms is ignored,  $N_i$  may be taken simply as the number of fully occupied sites. For heavy atoms, (18.5.6.4) must be used for  $N_i$ .

Equation (18.5.6.5) is not to be regarded as having absolute validity. It is a quick and rough guide for the diffraction-data-only error component for an atom with Debye  $B$  equal to the  $B_{\text{avg}}$  for the structure. It is named the *diffraction-component precision index*, or DPI. It contains none of the restraint data.

18.5.6.3. Extension for low-resolution structures and use of  $R_{\text{free}}$ 

For low-resolution structures, the number of parameters may exceed the number of diffraction data. In (18.5.6.3) and (18.5.6.5),  $p = n_{\text{obs}} - n_{\text{params}}$  is then negative, so that  $\sigma(x)$  is imaginary. This difficulty can be circumvented *empirically* by replacing  $p$  with  $n_{\text{obs}}$  and  $R$  with  $R_{\text{free}}$  (Brünger, 1992). The counterpart of the DPI (18.5.6.5) is then

$$\sigma(x, B_{\text{avg}}) = 1.0(N_i/n_{\text{obs}})^{1/2}C^{-1/3}R_{\text{free}}d_{\text{min}}. \quad (18.5.6.6)$$

Here  $n_{\text{obs}}$  is the number of reflections included in the refinement, not the number in the  $R_{\text{free}}$  set.

It may be asked: how can there be any estimate for the precision of a coordinate from the diffraction data only when there are insufficient diffraction data to determine the structure? By following the line of argument of Cruickshank's (1960) analysis, (18.5.6.6) is a rough estimate of the square root of the reciprocal of one diagonal element of the diffraction-only least-squares matrix. All the other parameters can be regarded as having been determined from a diffraction-plus-restraints matrix.

Clearly, (18.5.6.6) can also be used as a general alternative to (18.5.6.5) as a DPI, irrespective of whether the number of degrees of freedom  $p = n_{\text{obs}} - n_{\text{params}}$  is positive or negative.

*Comment.* When  $p$  is positive, (18.5.6.6) would be exactly equivalent to (18.5.6.5) only if  $R_{\text{free}} = R[n_{\text{obs}}/(n_{\text{obs}} - n_{\text{params}})]^{1/2}$ . Tickle *et al.* (1998b) have shown that the expected relationship in a restrained refinement is actually

$$R_{\text{free}} = R\{[n_{\text{obs}} + (n_{\text{params}} - h)]/[n_{\text{obs}} - (n_{\text{params}} - h)]\}^{1/2}, \quad (18.5.6.7)$$

where  $h = n_{\text{restraints}} - \sum w_{\text{geom}}(\Delta Q)^2$ , the latter term, as in (18.5.3.1), being the weighted sum of the squares of the restraint residuals.

## 18.5.6.4. Position error

Often an estimate of a position error  $|\Delta \mathbf{r}|$ , rather than a coordinate error  $|\Delta x|$ , is required. In the isotropic approximation,

$$\sigma(r, B_{\text{avg}}) = 3^{1/2}\sigma(x, B_{\text{avg}}). \quad (18.5.6.8)$$

Consequently, the DPI formulae for the position errors are

$$\sigma(r, B_{\text{avg}}) = 3^{1/2}(N_i/p)^{1/2}C^{-1/3}Rd_{\text{min}} \quad (18.5.6.9)$$

with  $R$  and

$$\sigma(r, B_{\text{avg}}) = 3^{1/2}(N_i/n_{\text{obs}})^{1/2}C^{-1/3}R_{\text{free}}d_{\text{min}} \quad (18.5.6.10)$$

with  $R_{\text{free}}$ .